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## **ROBOT-ORIENTED DESIGN**

For this topic we are specifically going to see some of the design oriented challenges that come in

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the way of designing a 4 wheel robot that uses Differential Steering for taking turns (left and right) or to make a Complete 360 Degree in-place (pivot) rotation (zero-radius turning). Attention to some basic details can help a beginner to make an efficient robot without loss of much energy and torque.

## **4 Wheel Robot Design using Differential Steering**

Robot-Oriented Design : Design and Management Tools for the Deployment of Automation and Robotics in Construction by Thomas Linner and Thomas Bock (2015, Hardcover)

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Synchronization of Organization, Building Structure, and Manufacturing Technology by Robot-Oriented Design Thomas Bock, Thomas Linner Design and Management Tools for the Deployment of Automation and Robotics in Construction Published online: 05 May 2015

## **Advanced Construction and Building Technology (Chapter 1 ...**

Robot-Oriented Design: Design and Management Tools for the Deployment of Automation and Robotics in Construction (The Cambridge Handbooks in Construction Robotics) eBook: Bock, Thomas, Linner, Thomas: Amazon.co.uk: Kindle Store

## **Robot-Oriented Design: Design and Management Tools for the ...**

Robotics design has historically been mired in engineering complexities, necessitating a systems oriented mindset at the expense of a user oriented one. Growth in pre-engineered resources, whether open source or commercial, enables a shift towards designing robots that fit their social contexts.

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